

## MINUTE FOR GROUP WORK



Education and Culture Lifelong learning programme COMENIUS

**COMENIUS School Partnerships** "European CNC-Network – Train for EUROPE – RELOADED"

Meeting Description	Fourth Project Meeting in Kuopio (Finland)
Meeting hosted by	Savon ammattii - ja aikuisopisto
Date / Time / Place	Monday, 17 <sup>th</sup> September 2012, Room No. C1234
Name of Workline	Workline A – Locomotive

Name of Workgroup	Group 2
Representative workgroup member	[IE] John O'Neill

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Co-representative workgroup member	
workgroup member	[IE] John O'Neill

Further workgroup members	[IE] George Ryan, Jack O'Neill, Andrew Plunkett, Oscar Burke, Ruben Collins, Brendan Doherty
	[HU] Norbert Zsido, Daniel Troppert
	[PT] Carlos Coimbra, Joao Martins, Paulo Carreira,
	[SI] Roman Zupanc, Feliks Lednik, Sašo Goubar, Miha Smodiš, Simona Vincelj
	[AT-STP] Friedrich Wilhelm, David Burisch, Matthias Kirbes, Stefan Wenighofer, Bernd Gutmann, Günter Amstätter
	[DE] Bernd Alles, Jörg Fritsch, Carla de Silva, Katrin Langel, Lukas Groth, Merlin Platz, Mike Fopke
	[LT] Edvinas Zilionis, Rita Jakstiene, Saulius Mereckas, Irmantas Matulaitis, Haroldas Jotautas

Minute written by	[SI] Simona Vincelj	

Description of work progress: Topics / Tasks / Results / Decisions / Facts of importance	Responsible school(s) or person(s) incl. deadlines
John O'Neill gave a short overview of the work done so far.	
<b>The Chassis</b> German team presented their proposal of the chassis with measurements. A decision on the measurements of the wheels must be made. German's proposal is 38 mm in diameter. The chassis should be just slightly shaped at the wheels.	
<b>The bogies</b> Austrian (STP) team presented their drawings. They have been in contact with German team. They think that the height must be changed and they should be put a bit higher.	
<b>The differential(s)</b> The Irish team showed the differential ordered by internet, which isn't complete yet. They also showed the differential from a radio controlled cars - useless because it's too big. When they get the complete differential, the dimensions will be put on the forum.	

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Decision: single differential, four wheel drive. We'll work on the transmission to both axles later on.			
<b>The motor</b> Slovenian team than Problems: they don't They showed three d	ked Mr Friedrich Wilh have the exact dimer lifferent motors:	elm for providing the motors. nsions yet.	
Motors			
TORQUE           1         203 Nm           2         245 Nm           3         105 Nm	SPEED 22,000 15,000 14,000	SIZE big small big	
They also presented lead, fits to the chass	specifications of the b sis, rechargeable.	pattery: cheap, heavy, made of	
The Housing Lithuanian team said demands. They show model). The lower str	that the housing coul ved the model made c raight part should be r	ld be easily adjusted to any further on Portugal drawings (wooden raised for 10-15 mm.	
<b>The wheel</b> The Hungarian team presented two different designs of the wheel and axle, and connections to bogie. Front wheels will come with bearings. Rear wheels will have bearings inside the connection element to bogie.			
Final decisions will be	e made tomorrow.		



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Meeting hosted by	Savon ammattii - ja aikuisopisto
Date / Time / Place	Thursday 20 <sup>th</sup> September 2012 Boom No. C1234

Date / Time / Place	Thursday, 20 September 2012, Room No. C1234
Name of Workline	Workline A – Locomotive
Name of Workgroup	Group 2

Representative workgroup member	[IE] John O'Neill
Co-representative workgroup member	

Further workgroup members	[IE] George Ryan, Jack O'Neill, Andrew Plunkett, Oscar Burke, Ruben Collins, Brendan Doherty
	[HU] Norbert Zsido, Daniel Troppert
	[PT] Carlos Coimbra, Joao Martins, Paulo Carreira,
	[SI] Roman Zupanc, Feliks Lednik, Sašo Goubar, Miha Smodiš, Simona Vincelj
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John O'Neill opened a discussion to establish the facts about the locomotive parts (what we know, what we don't know and what we have to do)		
The chassis We know: - dimensions 106 x 400	>	[DE]
<ul> <li>Material administration</li> <li>bogie position and size</li> <li>We don't know:</li> <li>position/size of battery, motor, drives</li> </ul>		[SI] gives the information to [DE] by the end of October
The bogie We know: - dimensions - material steel		[AT STP]
We don't know: - axle size		

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The wheels We know: - material aluminium - dimensions We don't know: - the hole in the centre ∞6/8 mm	<b>A</b>	[IR] checks this with [AT STP] Axle and the wheel tolerance [AT STP] and [HU]
The motor We know: - battery size, shape, weights - electronic control - motor we'll have 3000 Rpm - material aluminium - dimensions We don't know: - no motor yet	A A A	[SI] Info to [DE] [SI] + [IE]
<ul> <li>drive to differential</li> <li>The differential(s)</li> <li>We know: <ul> <li>all dimensions</li> <li>ratio =3:1</li> </ul> </li> <li>We don't know: <ul> <li>position on chassis</li> <li>dimensions of rear "bogie"</li> </ul> </li> </ul>	*	[IE] [IE] and [HU] have to decide on axle size
<ul> <li>3 mm thick (20 mm skirt - the vertical section)</li> <li>total height = 120 mm (400x100?) (PT + LT)</li> </ul>		



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Meeting Description	Fourth Project Meeting in Kuopio (Finland)
Meeting hosted by	Savon ammattii - ja aikuisopisto
Date / Time / Place	Friday, 21 <sup>st</sup> September 2012, Room No. C1234

Name of Workline	Workline A – Locomotive
Name of Workgroup	Group 2

Representative workgroup member	[IR] John O'Neill
Co-representative workgroup member	

Further workgroup members	[IR] George Ryan, Jack O'Neill, Andrew Plunkett, Oscar Burke, Ruben Collins, Brendan Doherty
	[HU] Norbert Zsido, Daniel Troppert
	[PT] Carlos Coimbra, Joao Martins, Paulo Carreira,
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Minute written by [SI] Simona Vincelj
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John O'Neill gave a short overview of the work done so far. We watched the video presentation of the locomotive group.	
Decisions made:	
The wheels - diameter of the wheels \&42, - the size of the axle \&5 - axle to axle 50mm [HU] + [IE]	≻ the wheels [HU] ≻[HU] + [IE]
The bogie	≻ the bogie [AT STP]
The chassis - buffer height 25mm - dimensions of chassis 100 (?) x400	≻buffers [DE] ≻chassis [DE]

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The motor - 3000 Rpm - the position of the motor- horizontally on the chassis The motor, the differential and wheels will be connected	➤ the motor [SI]
<b>The differential(s)</b> How to connect the differential, chains or gear? To be decided by Ireland.	≻[IE]
The Housing <ul> <li>3mm thick (20 mm skirt - the vertical section)</li> <li>total height = 120 mm (400x100?) (PT + LT)</li> </ul>	≻ the housing [PT]+ [LT]